

# THE POINCARÉ CONJECTURE

## LX 2009

Nicholas Jackson

Easter 2009

# “I SEE DEAD PEOPLE”



Cimetière du Montparnasse, Paris



*Poincaré*



**Jules Henri Poincaré (1854–1912)**



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- Cousin of Raymond Poincaré, President of France 1913–1920.

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If it looks like a sphere, it is.

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An  $n$ -dimensional manifold (or  $n$ -manifold) is an object which locally looks like ordinary, flat, Euclidean  $n$ -dimensional space ( $\mathbb{R}^n$ ) or half-space ( $\mathbb{R}^{n-1} \times \mathbb{R}^+$ ).

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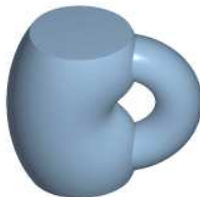
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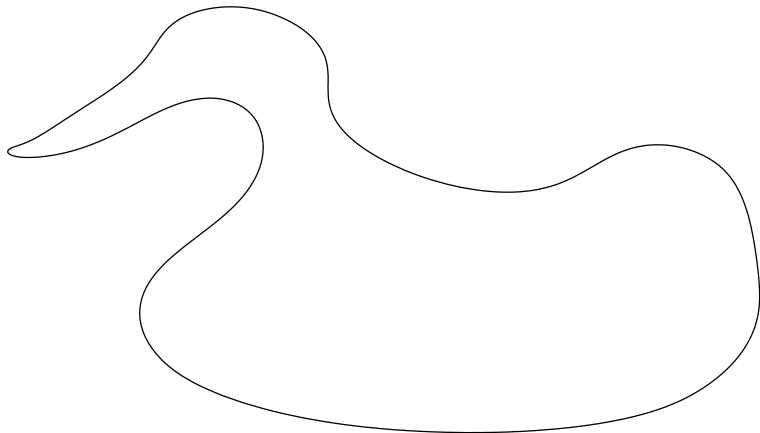


*A topologist is a person who does not know the difference between a doughnut and a coffee cup.*

– John L Kelley

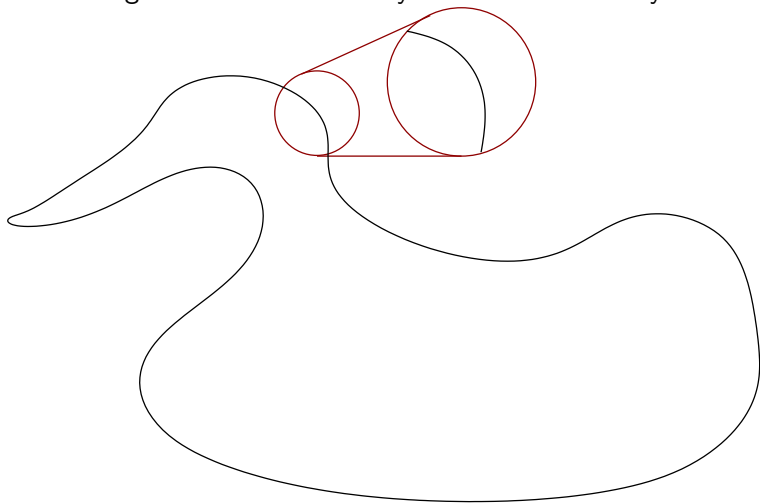
# EXAMPLE

The following closed curve is locally 1-dimensional everywhere:



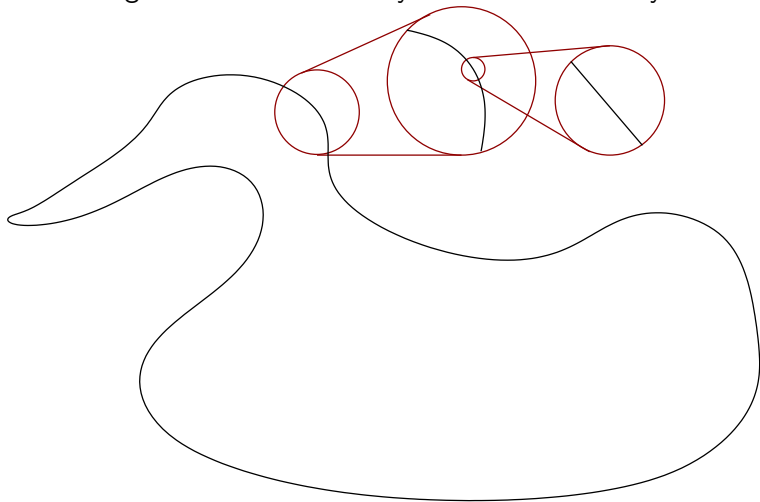
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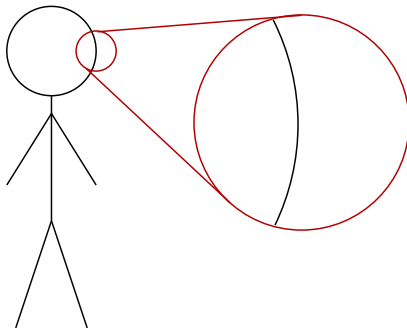




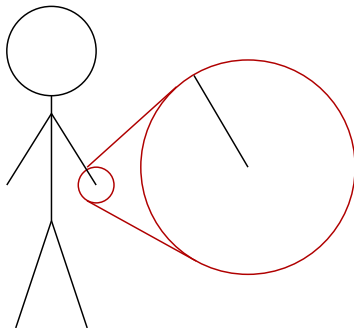
The following shape is not locally 1-dimensional everywhere:



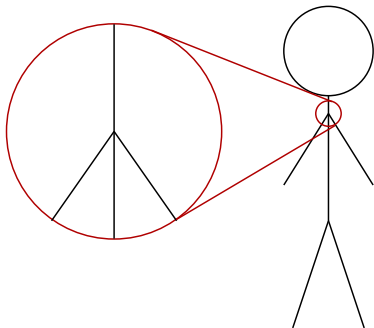
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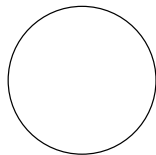
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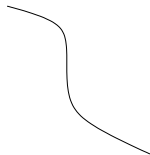
- An ant walking around on the surface of a football has two degrees of freedom.
- Fish and birds have three degrees of freedom.
- Flying cars are a very bad idea.

# CLASSIFICATION OF 1-MANIFOLDS

There are two different sorts of 1-manifolds:



$S^1$



$D^1$

All 1-manifolds are composed of disjoint copies of these.

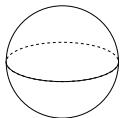
## COROLLARY

*All 1-manifolds have a non-negative, even number of boundary components (ends).*

# CLASSIFICATION OF 2-MANIFOLDS (SURFACES)

Start with the closed (boundaryless) ones.

The **2-sphere**,

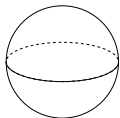


$S^2$

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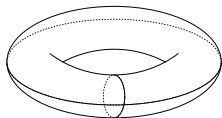
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The **2-sphere**,



$$S^2$$

the **torus**,

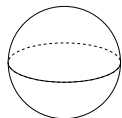


$$T^2 = S^1 \times S^1$$

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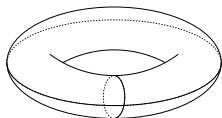
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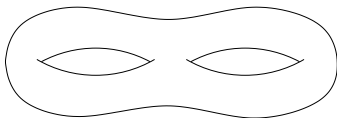
$$S^2$$

the torus,



$$T^2 = S^1 \times S^1$$

the double torus,

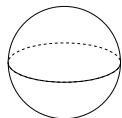


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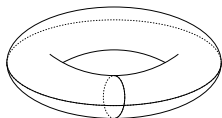
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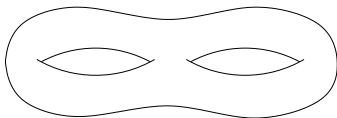
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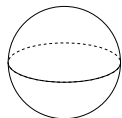
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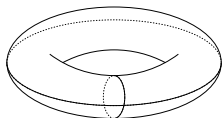
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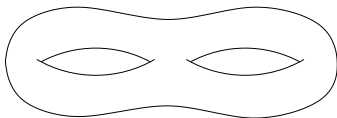
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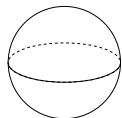
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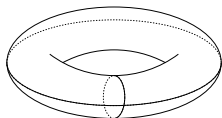
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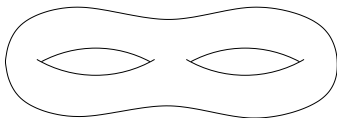
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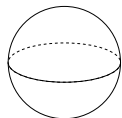
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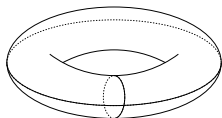
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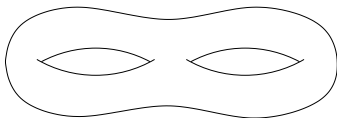
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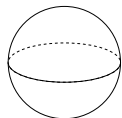
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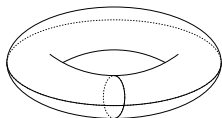
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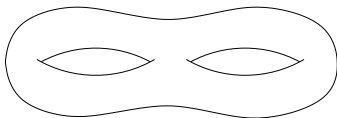
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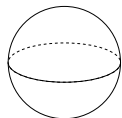
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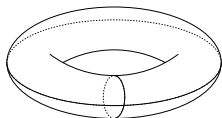
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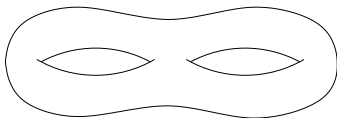
the **torus**,



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$$S_2$$

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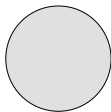
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$S_g$  is the surface of **genus**  $g$  (number of toroidal holes).

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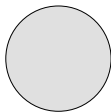
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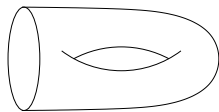
$D^2$

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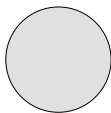
$D^2$



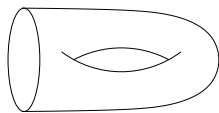
$T^2 \# D^2$

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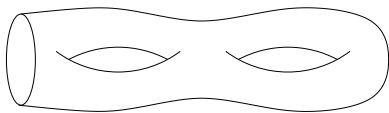
Now the ones with one boundary component:



$D^2$



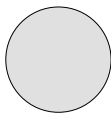
$T^2 \# D^2$



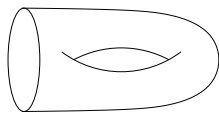
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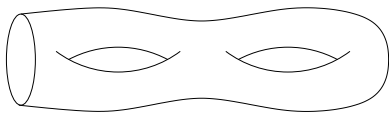
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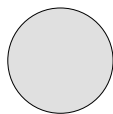
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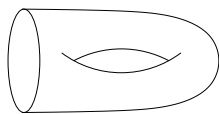
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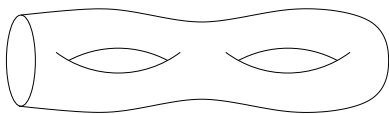


$D^2$

$S_{0,1}$



$T^2 \# D^2$



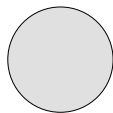
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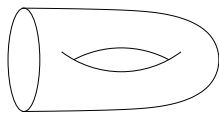
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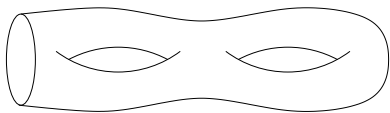
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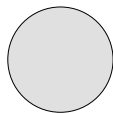
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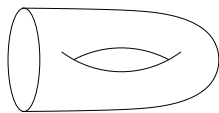
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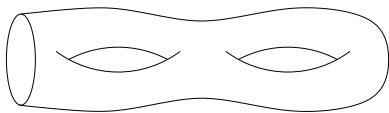
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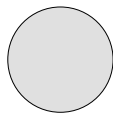
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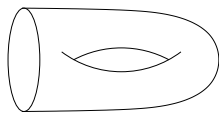
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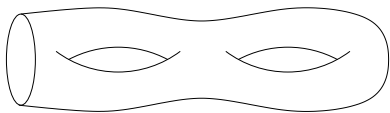
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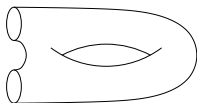
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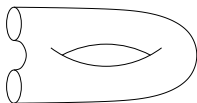
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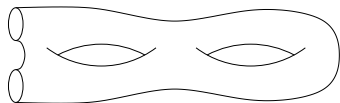
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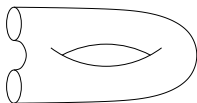


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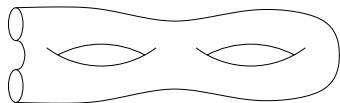
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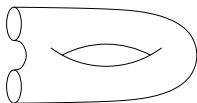
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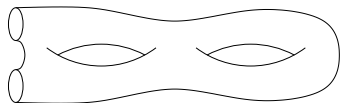
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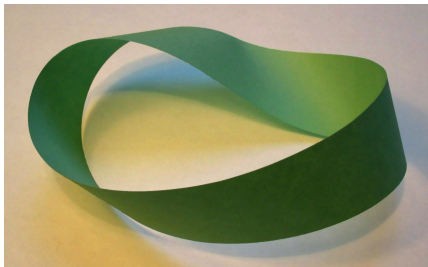
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$S_{g,b}$  is the surface of genus  $g$  with  $b$  boundary components.

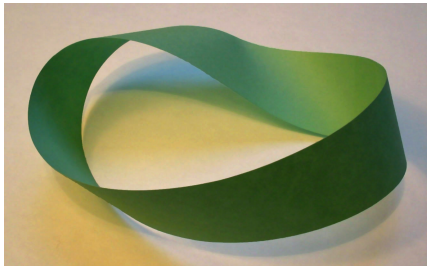
This isn't the full story. . .

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Möbius strip

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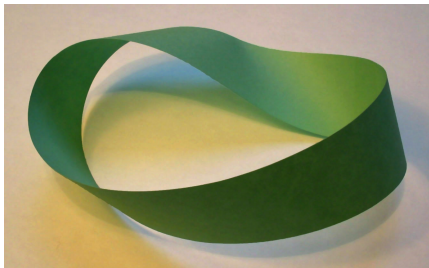


Möbius strip



Klein bottle

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Möbius strip

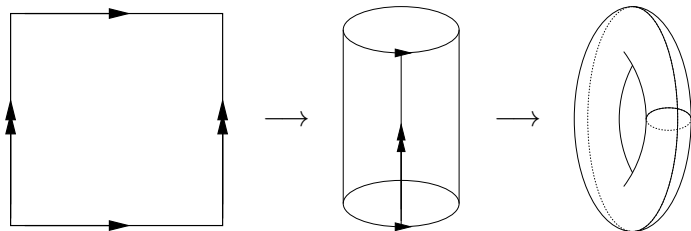


Klein bottle

The classification theorem can be extended to cover nonorientable surfaces like this.

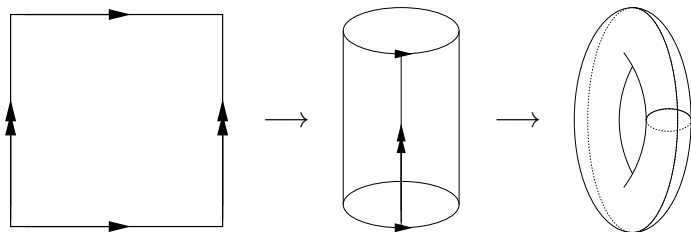
# IDENTIFICATION SPACES

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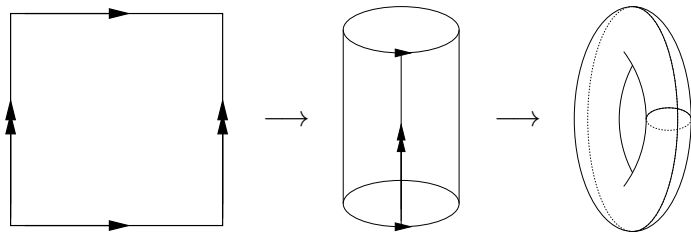


An ant walking around on this square will think it's living on a torus.



# IDENTIFICATION SPACES

We can make a torus by **identifying** (gluing together) the edges of a square in a particular way:



An ant walking around on this square will think it's living on a torus. This may be familiar to those of you who remember the 1980s...

# IDENTIFICATION SPACES

This is just like Asteroids:



We can make any (orientable or nonorientable) surface like this.

Where do we start with 3-manifolds?

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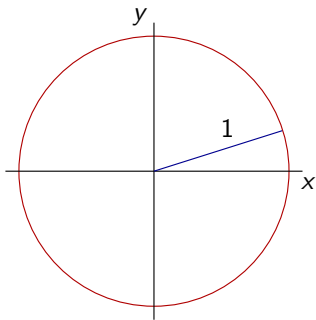
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- Therefore the simplest closed 3-manifold should be the 3-sphere  $S^3$ .

So what is it?

# THE 3-SPHERE

Extrinsically:  $S^1 = \{(x, y) : \sqrt{x^2 + y^2} = 1\} \subset \mathbb{R}^2$

This is the set of points at unit distance from the origin in the plane.

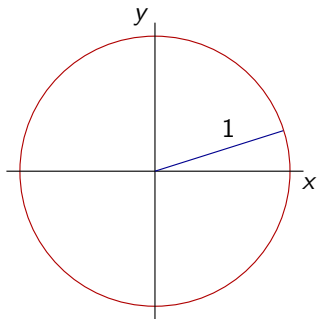




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Similarly

$$S^2 = \{(x, y, z) : \sqrt{x^2 + y^2 + z^2} = 1\} \subset \mathbb{R}^3$$

(the set of all points at unit distance from the origin in 3-space).

# THE 3-SPHERE

So, we could define

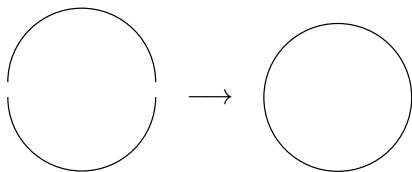
$$S^3 = \{(x, y, z, w) : \sqrt{x^2 + y^2 + z^2 + w^2} = 1\} \subset \mathbb{R}^4$$

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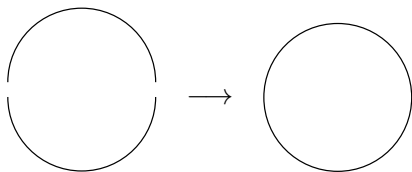


# THE 3-SPHERE

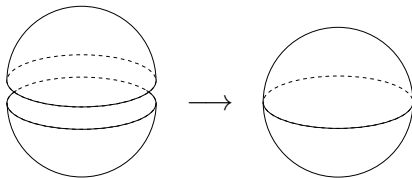
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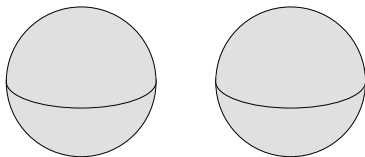
Alternatively, we can make the circle  $S^1$  by gluing together two line segments by their endpoints:



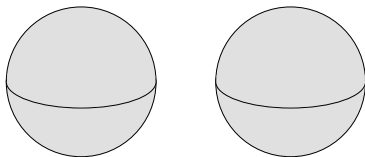
And we can make  $S^2$  by gluing together two discs along their edges:



So, by analogy, we should be able to construct  $S^3$  by gluing together two solid 3-balls along their bounding surfaces.

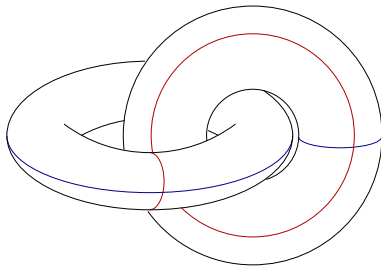


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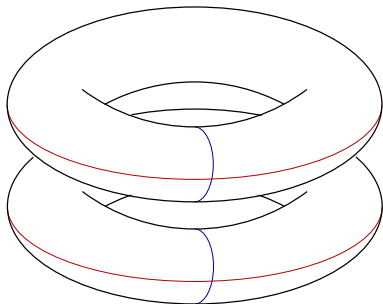


Not very easy to visualise extrinsically, but imagine a 3-dimensional game of Asteroids.

Another way is to glue two solid tori together along their boundaries, so that the meridional circle of one is lined up with the longitudinal circle of the other, and vice versa.

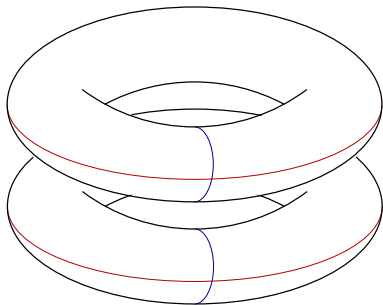


If, on the other hand, we glue the meridional circles to each other, and the longitudinal circles to each other, we get a different 3-manifold ( $S^2 \times S^1$ ) instead:





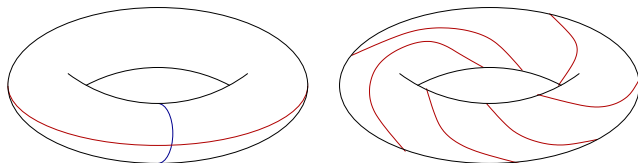
If, on the other hand, we glue the meridional circles to each other, and the longitudinal circles to each other, we get a different 3-manifold ( $S^2 \times S^1$ ) instead:



One way to tell that this isn't  $S^3$  is by looking at closed loops in the manifold.  $S^3$  is **simply-connected** (all closed loops can be shrunk down to a point) but this manifold isn't.

# LENS SPACES

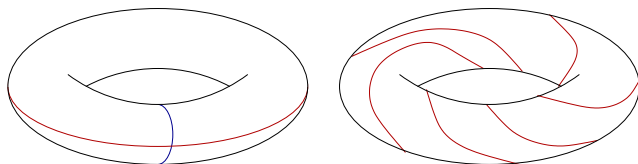
More generally, glue the meridian on one torus to a  $(p, q)$ -curve on the other.



This gives the **lens space**  $L_{p,q}$ .

# LENS SPACES

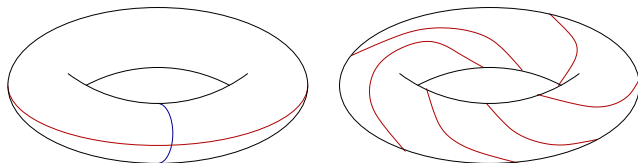
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This gives the **lens space**  $L_{p,q}$ .

In particular,  $L_{0,1} = S^3$  and  $L_{1,0} = S^1 \times S^2$ .

In general,  $L_{p,q}$  isn't simply-connected: there exist closed loops that can only be shrunk down to a point modulo  $p$ .

Another way of looking at this is to say that we can get any lens space  $L_{p,q}$  by taking  $S^3$ , cutting out a solid torus, and gluing it back in with a twist.

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This procedure is called **surgery**. If we use a  $(p, q)$ -curve it's **rational surgery**, if we just use a  $(p, 1)$ -curve it's **integer surgery**.

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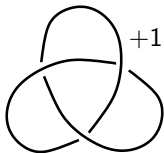
This procedure is called **surgery**. If we use a  $(p, q)$ -curve it's **rational surgery**, if we just use a  $(p, 1)$ -curve it's **integer surgery**. More generally, we can do this with a knotted solid torus (or tori):

## THEOREM (LICKORISH–WALLACE THEOREM)

*Any compact, orientable, closed 3-manifold can be constructed from  $S^3$  by integer surgery on a knot or link.*

# DODECAHEDRAL SPACE

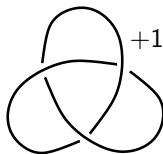
Integer surgery on a right-handed trefoil with framing  $+1$  gives a 3-manifold called the **Poincaré homology sphere** or **Poincaré dodecahedral space**.



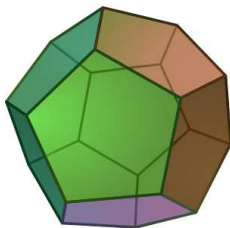


# DODECAHEDRAL SPACE

Integer surgery on a right-handed trefoil with framing  $+1$  gives a 3-manifold called the **Poincaré homology sphere** or **Poincaré dodecahedral space**.



Alternatively, take a solid dodecahedron and identify opposite faces with a  $36^\circ$  twist.



# THE POINCARÉ CONJECTURE

The Poincaré Conjecture says that  $S^3$  is the only compact simply-connected 3-manifold.

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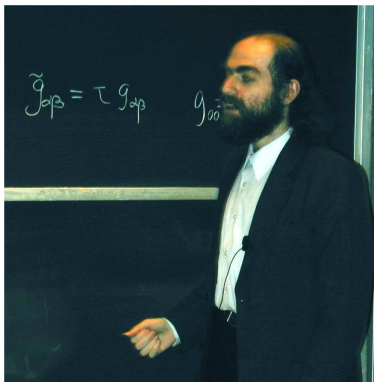
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In 1982, William Thurston formulated the **Geometrisation Conjecture**, which says that all compact 3-manifolds can be decomposed into submanifolds with one of eight geometric structures. The Poincaré Conjecture is a corollary of the Geometrisation Conjecture.

# THE POINCARÉ CONJECTURE

In 2002–2003, the Russian mathematician Grigori Perelman posted three papers on the arXiv containing a proof of the Poincaré Conjecture and the Geometrisation Conjecture, using a technique called **Ricci flow** devised some years earlier by Richard Hamilton.



# THE END

