

Confined three-dimensional stability analysis of the cylinder wake

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A spatially confined stability analysis is reported for the cylinder wake at Reynolds numbers 190 and 260. The two three-dimensional instabilities at these Reynolds numbers are shown to be driven by the flow just behind the cylinder.

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Consider the von Kármán vortex street generated by flow past an infinitely long circular cylinder. This flow is time periodic and two dimensional for Reynolds numbers between approximately 47 and 189 [1–4]. (The Reynolds number is $Re \equiv U_\infty d / \nu$, where U_∞ is the fluid velocity far from the cylinder, d is the cylinder diameter, and ν is the kinematic viscosity.) At Reynolds number 189 the two-dimensional (2D) vortex street becomes three-dimensionally unstable [3–7]. A numerical stability analysis of the flow up to Reynolds number 300 has determined two separate bands of linearly unstable modes [5]. The first appears at $Re=189$ with a spanwise wavelength of 4 cylinder diameters and the second appears at $Re=260$ with a spanwise wavelength of 0.8 diameters. These linear instabilities are related to three-dimensional (3D) shedding modes known as mode *A* and mode *B*, first observed experimentally by Williamson [3].

In this paper I revisit the stability analysis of the vortex street. I show that small regions of the full flow just behind the cylinder are responsible for the 3D linear instabilities despite the fact that the actual linear modes extend many cylinder diameters downstream of the cylinder. This is important for two separate reasons. The first is that this limits the regions that should be analyzed either to clarify instability mechanisms or to suppress the instabilities if so desired. The second reason is that the stability analysis of small flow regions is computationally very efficient compared with a stability analysis of the full flow field. Thus this approach provides a method for quickly obtaining approximate stability information about a complex flow.

The computational approach is described fully elsewhere [5]. I summarize briefly the main points with focus on the important aspects for the current work. First, direct simulations of the incompressible Navier-Stokes equations are used to obtain 2D, time-periodic wake flows: $\mathbf{U}(x, y, t+T) = \mathbf{U}(x, y, t)$ where T is the wake period. A spectral-element method is employed on a computational domain shown in Fig. 1. The length scale is the cylinder diameter. The size of the computational domain depends on the Reynolds number and the accuracy required [5]. The domain shown gives sufficiently accurate results for the purposes of this work.

The boundary conditions imposed for the computation of \mathbf{U} are as follows. On the top, bottom, and left boundaries uniform flow is imposed $\mathbf{U} = (U, V) = (1, 0)$. At the right edge

a (Neumann) outflow boundary condition for the velocity and pressure P is used

$$\partial U / \partial x = 0, \quad \partial V / \partial x = 0, \quad P = 0. \quad (1)$$

No-slip conditions are imposed at the cylinder surface.

The next step is a Floquet stability analysis of 3D disturbances to the 2D wake. This analysis is based on the evolution of infinitesimal 3D perturbations $\mathbf{u}'(x, y, z, t)$ of the 2D flow $\mathbf{U}(x, y, t)$. The equation for such a perturbation is obtained by linearizing the Navier-Stokes equations about \mathbf{U}

$$\frac{\partial \mathbf{u}'}{\partial t} = -(\mathbf{U} \cdot \nabla) \mathbf{u}' - (\mathbf{u}' \cdot \nabla) \mathbf{U} - \frac{1}{\rho} \nabla p' + \frac{1}{Re} \nabla^2 \mathbf{u}', \quad (2)$$

where p' is the perturbation to the pressure that enforces $\nabla \cdot \mathbf{u}' = 0$.

In this Brief Report I shall primarily consider Eq. (2) posed on subdomains such as that illustrated in Fig. 1. These subdomains are characterized by their inflow and outflow

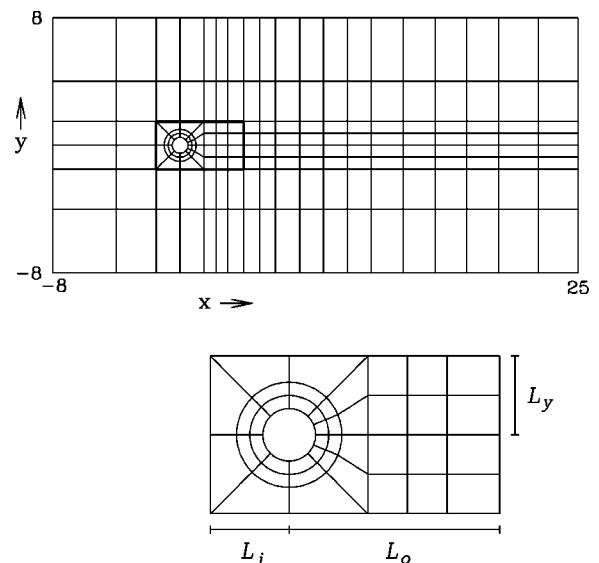


FIG. 1. Spectral-element computational mesh. The base flow is computed on the full domain and stability computations are performed on the full domain and on a variety of subdomains. The subdomain outlined in bold and shown as an enlargement has inflow length $L_i=1.5$, outflow length $L_o=4$, and cross-stream height $L_y=1.5$.

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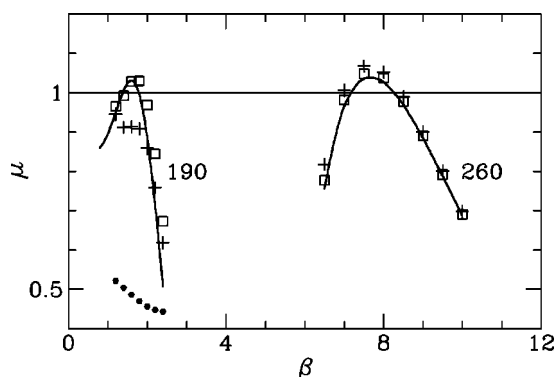


FIG. 2. Summary of Floquet multipliers at $Re=190$ and $Re=260$ (as labeled) for β near the critical value in each case. Solid curves are from computations on the full domain. Points are from subdomains with $L_i=0$, $L_y=1.5$, and $L_o=3$ (squares), $L_o=2.25$ (crosses), and $L_o=1.5$ (dots). The multipliers for $Re=260$, $L_o=1.5$ are off the scale of the figure.

lengths L_i and L_o , measured with respect to the cylinder center, and their cross-flow range $-L_y \leq y \leq L_y$. The base flow \mathbf{U} appearing in Eq. (2) is obtained by restricting the base flow from the full domain to the appropriate subdomain.

Boundary conditions on \mathbf{u}' are required by Eq. (2). Consider the standard case in which \mathbf{u}' is computed on the same domain as \mathbf{U} . Then the requirement that $\mathbf{U}+\mathbf{u}'$ satisfies the same boundary conditions as \mathbf{U} gives homogeneous boundary conditions on \mathbf{u}' : $\mathbf{u}'=(0,0,0)$ on all domain boundaries except the outflow boundary where \mathbf{u}' satisfies the analogy of Eq. (1). One can view these boundary conditions as the requirement that the perturbation be zero at the inflow and lateral boundaries of the domain but that perturbations can advect out of the domain. Based on this reasoning we impose these homogeneous boundary conditions when computing \mathbf{u}' on subdomains. We are interested in examining perturbations \mathbf{u}' that are zero on all boundaries of the subdomain except the outflow boundary. Perturbations are allowed to advect out of the subdomain.

From the linearized equations the spectrum of Floquet multipliers μ and corresponding Floquet modes $\tilde{\mathbf{u}}$ can be found [5]. Exponentially growing perturbations correspond to multipliers outside the unit circle in the complex plane ($|\mu| > 1$). Because the geometry is homogeneous in the spanwise direction, Floquet modes decouple in spanwise wave number β . The Floquet multipliers are thus computed as a function of β on a number of subdomains for $Re=190$ and $Re=260$, just above the critical Reynolds numbers for the 3D instabilities.

Figure 2 summarizes the study in terms of multiplier spectra while Figs. 3 and 4 shows representative Floquet modes. A large number of subdomains have been studied but only representative cases are shown near the minimum dimensions necessary to capture the 3D instabilities.

Figure 2 primarily demonstrates the effect of outflow length L_o on the Floquet multiplier spectrum. The inflow length and cross-stream height are fixed at minimal values of $L_i=0$ and $L_y=1.5$. One sees that $L_o=3$ is sufficient to capture the destabilizing Floquet mode. Increasing L_o further has almost no effect. For $Re=190$, decreasing L_o to 2.25 causes a

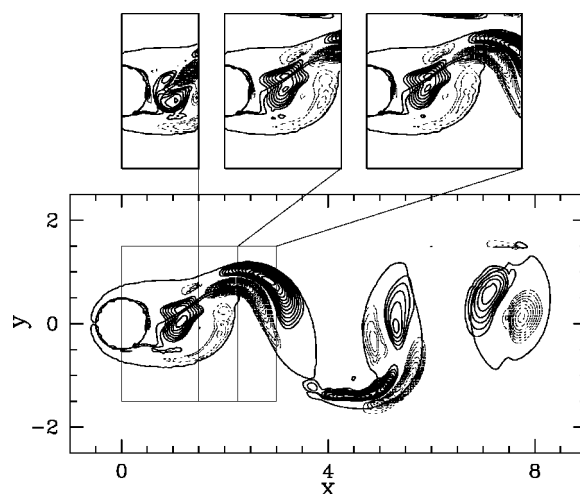


FIG. 3. Floquet modes at $Re=190$ with $\beta=1.6$. The main figure shows (a portion of) the mode computed on the full domain. Insets show modes computed on the subdomains indicated. (The inflow boundary $L_i=0$ and the lateral boundaries $L_y=1.5$ are the same for all subdomains.) All modes are plotted as spanwise vorticity contours at the same fixed time. The spanwise vorticity contours ± 0.4 of the base flow are also plotted.

substantial change to the spectrum—the subdomain is evidently too small to capture all the relevant flow features that drive the instability. In the case of $Re=260$, decreasing L_o to 2.25 causes only a small change to the spectrum and the subdomain is essentially still large enough to capture relevant flow features. Decreasing the outflow length to $L_o=1.5$ causes the spectrum in both cases to deviate wildly from the correct behavior (at $Re=260$ the multipliers become complex with large magnitude and cannot be plotted on the scale of Fig. 2). Figs. 3 and 4 show just how well the Floquet modes are captured by the subdomain computations even though the Floquet mode on the full domain extends far downstream of the cylinder [5].

Increasing the inflow length L_i has some effect on the spectrum of multipliers in the case of $Re=190$. However, the

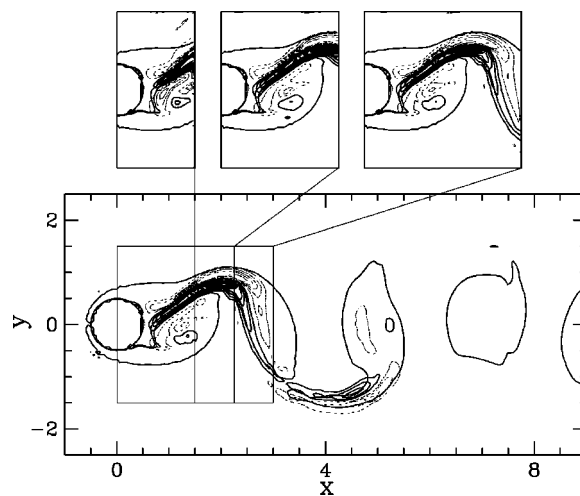


FIG. 4. Floquet modes at $Re=260$ with $\beta=7.7$ using the same conventions as Fig. 3.

effect is very small at the critical wave number where the multiplier branch has largest magnitude. Increasing the inflow length has almost no effect in the case $Re=260$. Increasing the cross-stream height has very little effect in either case. It is possible, in fact, that the cross-stream height could be reduced slightly from that used here without compromising the accuracy of the multipliers.

It is reasonable to conclude that the physical region responsible for the instability is localized within the subdomain in those cases where the Floquet multipliers and Floquet modes from subdomains are close to those from the full domain. This localization of the instability is similar to the transition from steady flow to vortex shedding that takes place at the primary wake instability. In that case there is a local, absolutely unstable region extending approximately three to four diameters downstream [8,9], very similar to the scales observed here. In fact the current computational analysis is similar in spirit to that of Hannemann and Oertel [8] and can be thought of as situated between the local analysis

of a parallel wake profile and the global analysis previously reported for the secondary instability to three dimensionality [5].

Finally, it is worth considering the stability of the downstream portion of the flow. In this case the base flow is projected onto the subdomain with $2.25 \leq x \leq 25$ and $-4 \leq y \leq 4$. At both $Re=190$ and $Re=260$ the flow in this downstream region is found to be very stable. The maximum modulus of the Floquet multipliers are $|\mu| \approx 0.28$ at $Re=190$, $\beta=1.6$ and $|\mu| \approx 0.19$ at $Re=260$, $\beta=7.5$.

In this Brief Report I have shown how a local Floquet stability analysis of small regions of the wake just behind a cylinder are sufficient to capture both 3D instabilities observed in wake transition. The specific results are of interest for future attempts to understand better the physical mechanisms of 3D transition [7,10–13] because the results set limits to the regions that could drive the instabilities. The general method is of interest for future computational studies of flow instabilities.

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